

SRS Series

Twin Square Rail Ball Screw Gantry System

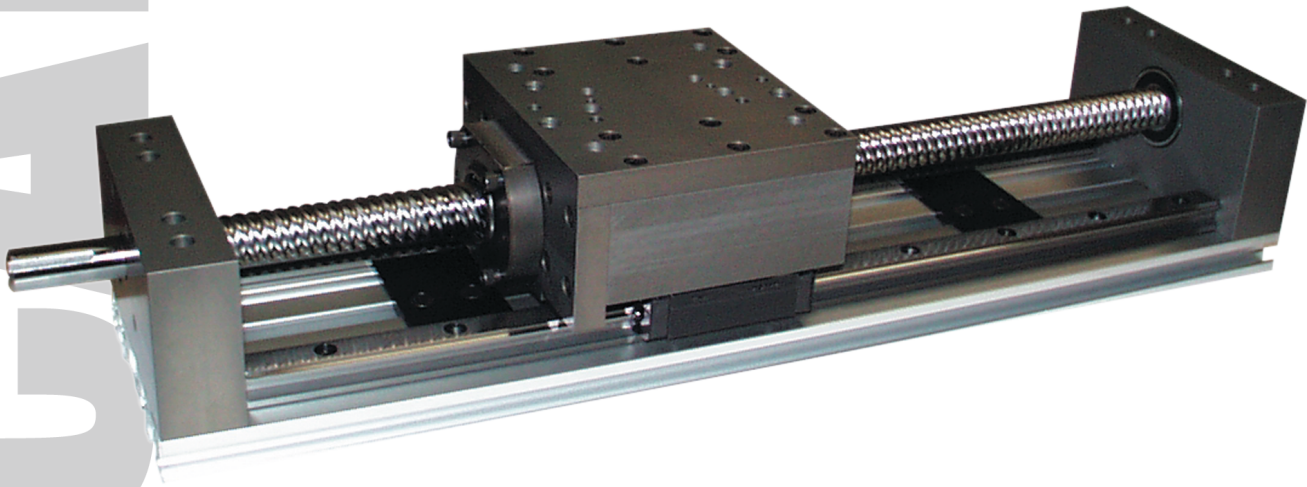


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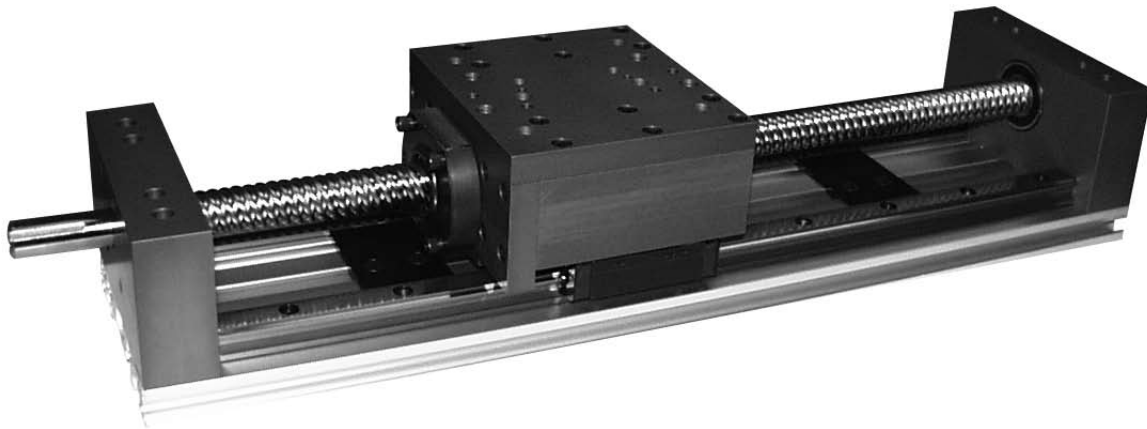
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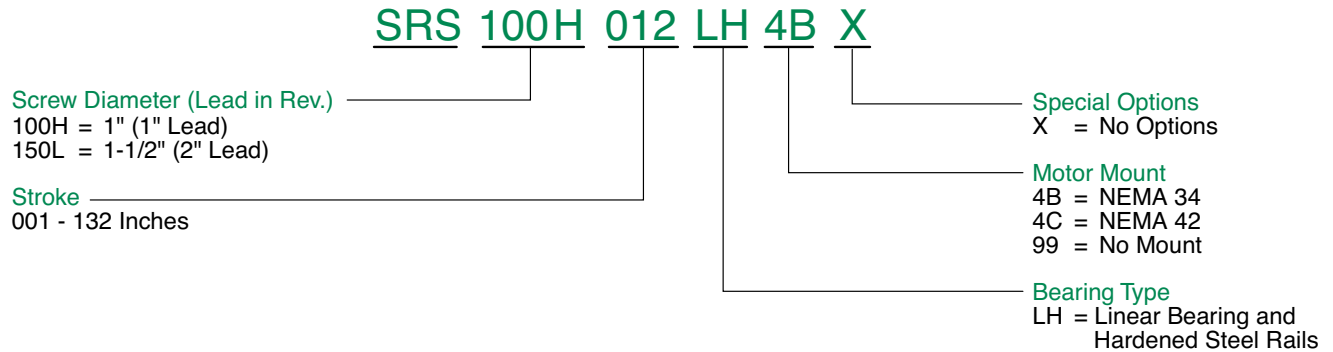
SRS - Twin Square Rail Ball Screw Gantry System

- * The ball screw gantry provides precise positioning and high load carrying capacity.
- * Thrust loads up to 7600 lbs.
- * Suitable for mounting in any position; horizontal, vertical, on an incline, or inverted.
- * Low torque required to drive the load due to high efficiency ball screw.
- * Linear bearings provide low stick slip for precise positioning and ease of moving the load.
- * Precision linear rail system supports the load through the entire stroke length.
- * Rugged aluminum extrusion supports the linear rail system through the entire stroke length.
- * Motor mounting for all NEMA 34 and 42 frame motors.
- * NEMA standard gearheads mount directly to the unit.
- * Stroke lengths to 11 feet.
- * NU-MATE mounting pattern is standard.
- * Minimal deflection due to the square rail support system.
- * Bellows available for severe duty applications.
- * Recirculating twin ball tracks in the screw and on the rails provide greater accuracy.
- * Load locking spring prevents load from free falling in the event the ball bearings are lost from the nut.
- * Brush wipers prevent contaminants from entering the nut.





How to Order



SRS Series Technical Specifications

DESCRIPTION	SRS100	SRS150
Maximum Stroke	11 feet	11 feet
Maximum Thrust Load-Dynamic	3450 lbs.	5200 lbs.
Accuracy	+/- 0.005	+/- 0.005
Repeatability	+/- 0.005	+/- 0.005
Screw Diameter	1.00	1.425
Screw Lead	1.00	2.000
Overall	12.31+stroke	12.31+stroke

Critical Speed Calculations

Note: 3000 RPM Max.

SRS100H

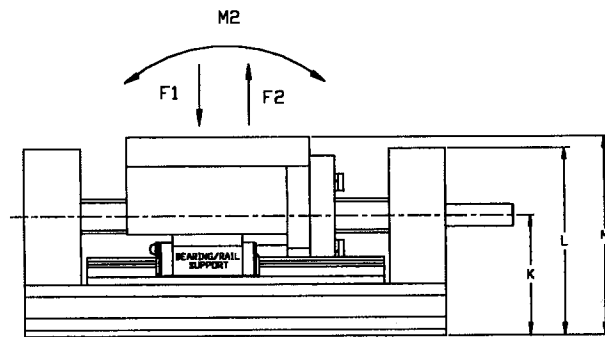
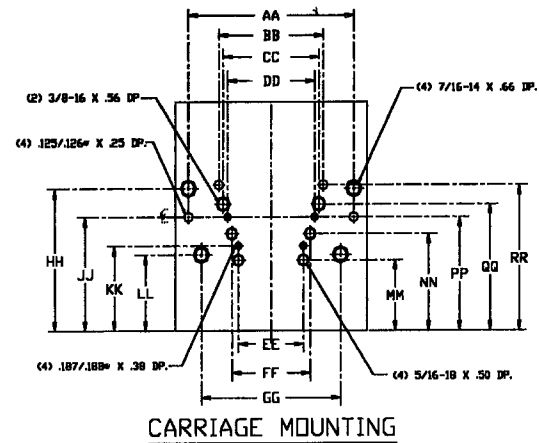
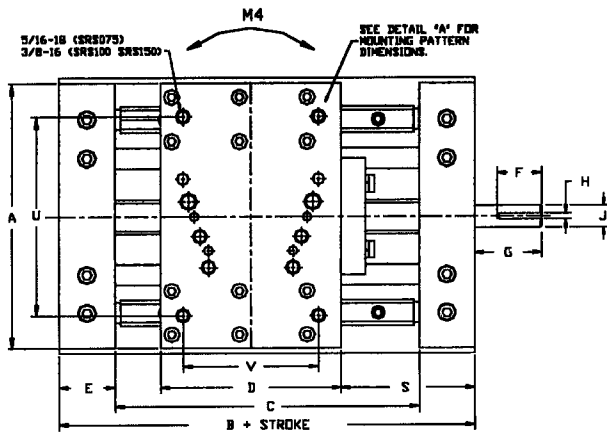
$$1 \times (4.76 \times 10^6) \times \left(\frac{0.911}{(\text{Stroke} + 9.31)^2} \right) = A \quad A \times 0.8 = B \quad \frac{B}{60} = C \quad C \times 1.0 = \text{In./Sec.}$$

SRS150L

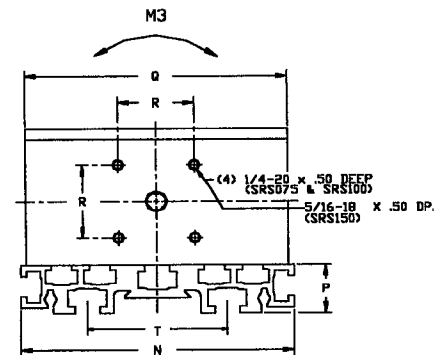
$$1 \times (4.76 \times 10^6) \times \left(\frac{1.323}{(\text{Stroke} + 9.31)^2} \right) = A \quad A \times 0.8 = B \quad \frac{B}{60} = C \quad C \times 2.0 = \text{In./Sec.}$$



SRS Series Dimensions



NOTE: UNIT IS DRAWN AT 0° STROKE



	A	B	C	D	E	F	G	H	J	K	L	M	N	P	Q	R	S	T
SRS100H	6.11	12.31	9.31	5.50	1.50	1.09	2.00	0.187	0.75	3.05	4.30	4.93	6.25	1.13	6.25	1.75	3.91	3.50
SRS150L	6.25	12.31	9.31	6.00	1.50	1.58	2.50	0.250	1.00	3.23	5.13	5.76	6.25	1.13	6.25	1.80	3.81	3.50

	U	V	AA	BB	CC	DD	EE	FF	GG	HH	JJ	KK	LL	MM	NN	PP	QQ	RR
SRS100H	4.00	4.00	4.75	3.00	2.75	2.50	—	2.25	4.00	3.80	3.05	—	2.05	—	2.61	3.05	3.40	3.90
SRS150L	4.00	4.00	4.75	3.00	2.75	2.50	—	2.25	4.00	3.80	3.13	—	2.13	—	2.34	2.78	3.13	3.63

Moment Load Rating

	SRS100H	SRS150L
F1	11,448 lbs	16,524 lbs
F2	7667 lbs	9792 lbs.
M2	3823 in/lbs	6514 in/lbs
M3	4389 in/lbs	7222 in/lbs
M4	3823 in/lbs	6514 in/lbs



Application Request Form for Belt and Screw Driven Electrical Products

Your Name: _____ Company Name: _____

Phone: _____ Fax: _____ Date: _____

Please Complete the required info in each step:

Stroke (inches): _____ **Load** (pounds): _____ -and/or- **Opposing Force** (pounds): _____

Repeatability: +/-0.005 inches (Screw Drive): ☐ -or- +/-0.012 inches (Belt Drive): ☐

Actuator Orientation: Horizontal: ☐ -or- Vertical: ☐ *Note: Belt Drive Product is not recommended for Vertical Applications*

Check box if carriage is face DOWN: _____ -and/or- Include Degree of Incline: _____°

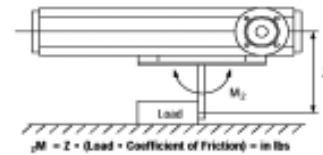
Check one:

A) Load is supported by Actuator: ☐ (if no skip to STEP 4)

B) Load is pushed by Actuator: ☐

If load is pushed: 1) What supports the load? _____

2) Coefficient of friction? _____



Moment Loading

Check one of the Following:

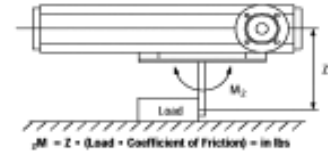
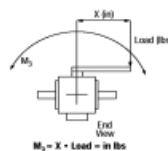
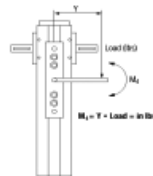
A) A Moment Condition does not occur: ☐ (if so skipt to STEP 5)

B). A Moment Condition does occur: ☐

CIRCLE ONE of the following conditions and provide the following information:

Arm Length (inches): _____

Force (pounds): _____



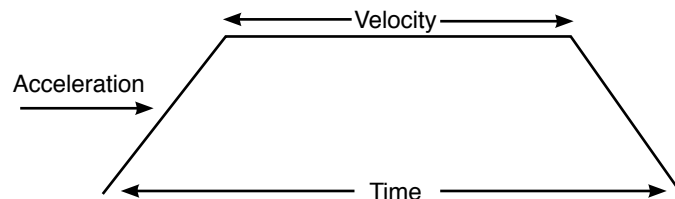
Speed/Cycle Time Fill out as much information as possible. Must include a move distance and at least 1 other input.

Move Distance: _____ inches

Velocity: _____ in/sec/

Acceleration: _____ in/sec²

Time: _____ sec



Note: Provide Move Distance and at least 1 other input

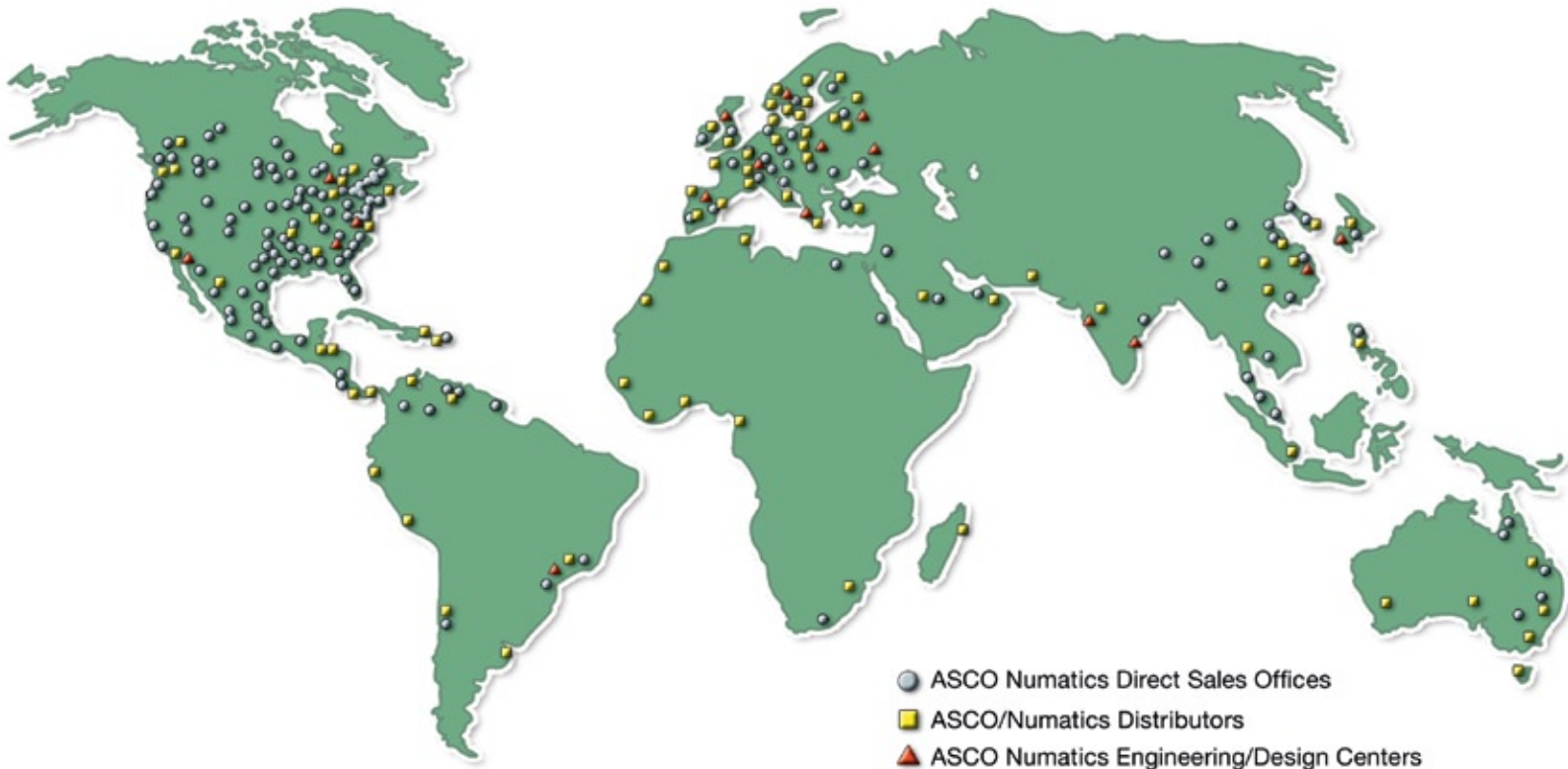
If there are multiple stops, check here: ☐ and provide Move Distance and at least one other input per stop in the space below:

Total Package? Please check all that apply: Motor & Controller Package: ☐ Brake: ☐

Customers Controller or PLC will supply host commands: ☐ Encoder/Closed Loop: ☐

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